Or EPICS – It Has Industry In Its Name.

Bob Dalesio - Short Bio

- Team Developed and applied the EMC Controls Emcon D3 Control System: Steel Plant Provo, Utah, Oil Refinery, Puerto Rico Early 80s
 This company was started by a group that split off from Foxboro
- Team Developed and applied the Computer Products Industry Control System: UTC Fuel Cell, %\$# and ^%\$ Laser Control Systems Mid 80s
- Team Developed and deployed the Ground Test Accelerator Control System aka Low Energy Development Accelerator in the late 80's
- Team Developed and supported the deployment of The Experimental Physics and Industrial Control System from 1990's to the present.

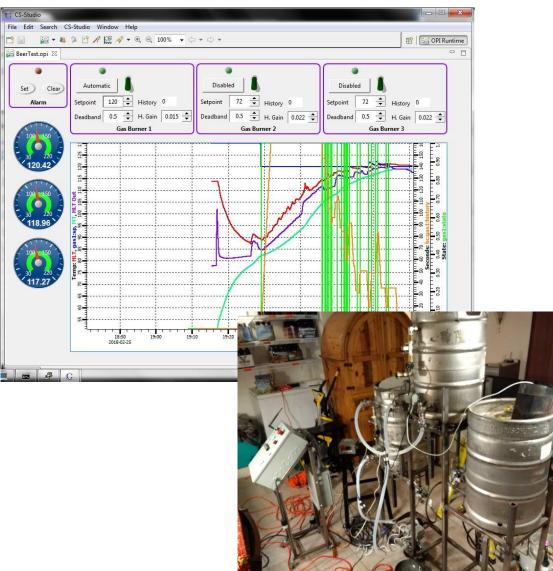
The Experimental Physics and Industrial Control System (EPICS)

- Was developed to provide tools for process control engineers with no programming.
- EPICS is widely used in Industrial and Research Applications of all Sizes.
- Architectural Features of EPICS support Industrial and Research Control
- Interfaces to support extensions and high-resolution timing
- Support from Commercial Companies for tools and application

EPICS at Large Facilities On All Continents



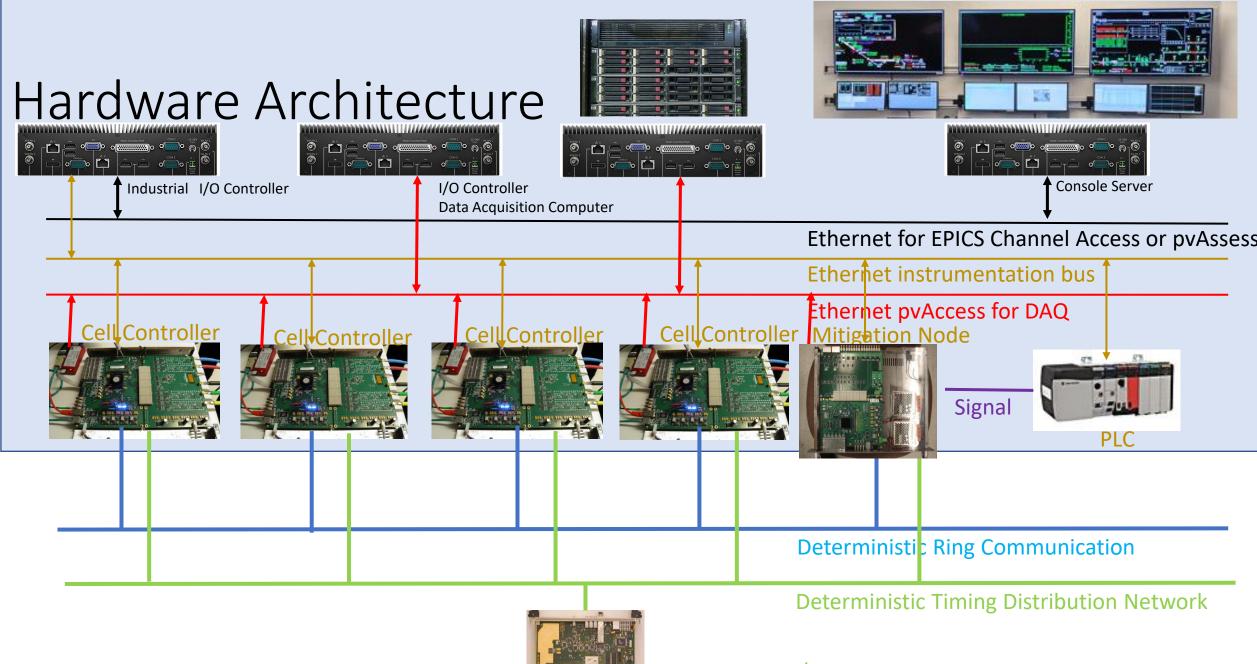
EPICS Scales Down to PCs and Raspberry Pi's



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Industrial IO is 60% of all IO at Accelerators

- Vacuum Control Vacuum Controllers and PLC IO
- Cryo Control CEBAF was the first facility to use EPICS for this
- Vibration Monitoring
- Cooling Water Control
- Temperature Monitoring
- Power Supplies: high voltage RF, regular and pulsed magnets
- Access Control into restricted areas
- Facility Control Sverdrup used EPICS for SNS facility with AB PLCs
- Power Distribution and rack monitoring



Master Pattern / EVENT Generator

Non-Industrial Instrumentation

- Beam Diagnostics (>300 MHz)
- Radio Frequency Field Control (>300 MHz)
- Fast Orbit Feedback (10 kHz)
- RF Phase Control (>300 MHz)
- Triggered acquisition (<10 psec jitter, <1nsec resolution)
- Fast corrector magnet power supplies (10 kHz)
- Beam Loss Detection (<3 usecs latency)
- Beam Loss Mitigation (<10 usec)
- Data Correlation (1 nsec)

Commercial Research and Development Agreements Yielded Three Partners in the 90'

- Baltimore Gas & Electric LNG terminal, Pipeline compressors (3)
- LOF Float glass manufacturing, Glass coating (3)
- NASA Satellite ground station instrument monitoring
- WLSSD Sewage treatment & incineration Liquid
 - S. Nevada Water treatment, pumping & storage
 - Citgo Refinery tank farm automation, Product movement
 - AMD Chip 'fab' environmental controls/HVAC
 - Gas SAIC Automated/portable weapons disposal
 - PIP tosAlamos Particle accelerator vacuum system control
 - **California ISO Power grid monitoring, metering** and AGC

Industrial Automation. Inc.

San Diego Gas & Electric – SCADA/Remedial Action System

City of N. Wales - Water pumping & distribution

- City of Milwaukee Sewage treatment & Water treatment (5)
- Nippon Sheet Glass Glass coating line Water ٠
- Anne Arundle Co. Waste treatment, Water treatment/distribution (6)
- Austin Regional Sewage treatment and collection/pumping Tong Yang Cement plant automation
- •
- S. Nevada Water distribution/pumping system expansion
- Citgo Lake Charles Tank farm automation
- Northwest Indiana Water treatment, storage er and distribution generation
- **River Mtn. Treatment Plant Water treatment,** and distribution

San Diego Gas & Electric - Distribution SCADA & load shedding



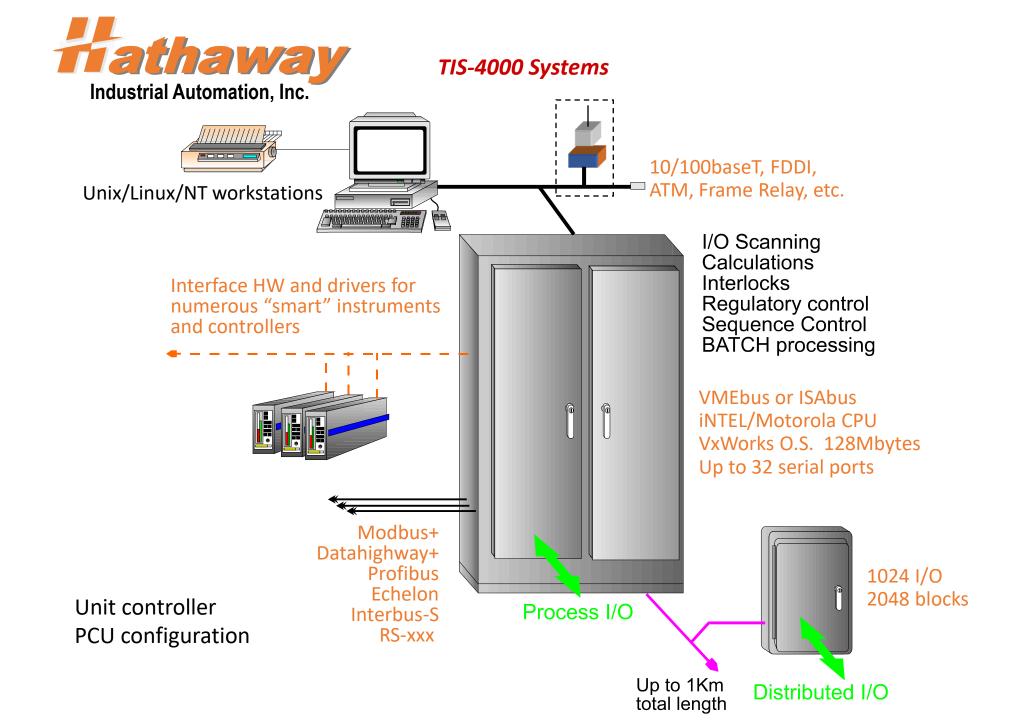
TIS-4000 Systems

Non-Traditional (Distributed) SCADA and DCS systems:

- Designed to provide for Inter/Intra/ExtraNet communications
- •Incorporates SSL layer TCP/IP plus digital "certs"/VPN technology
- •Uses "digital" communication systems
- •Works well at 56Kbps and better with more bandwidth
- •Uses a "publish and subscribe" data exchange methodology
- •Co-exists with other traffic (video, VoIP, data, FTP, etc.)
- •Can be part of a "hybrid" system (traditional plus distributed)

"REPLACE IN PLACE" was the marketing approach to integrate existing systems

..... and then upgrade incrementally





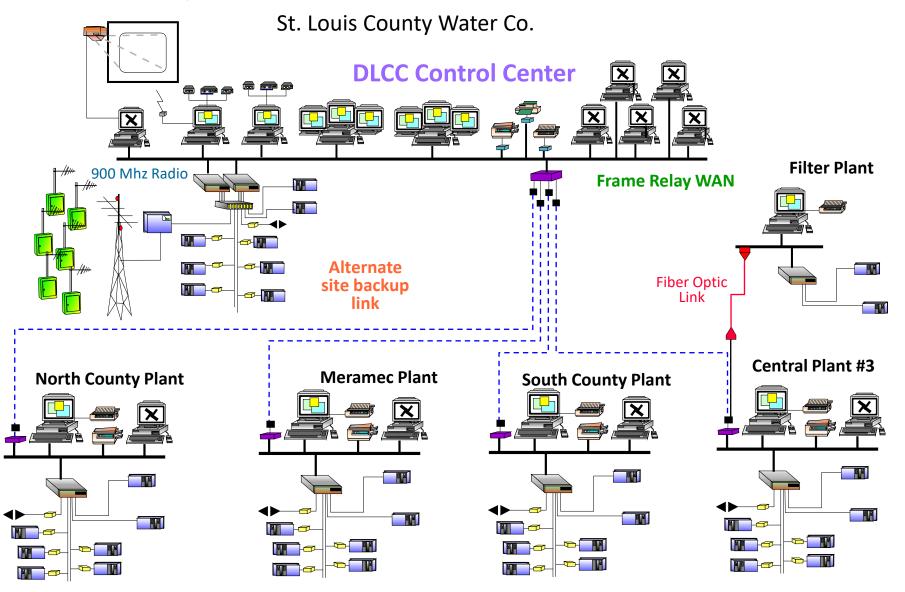
TIS-4000 Systems

ISAbus RSU Pentium II CPU TE PLC remote unit Floor mounted "Smart" RTU VMEbus RSU M68040 CPU Pole-top RMS900 "Smart" RTU 6 MS-900 DA CON Hathaway Automation Technology



Industrial Automation, Inc.

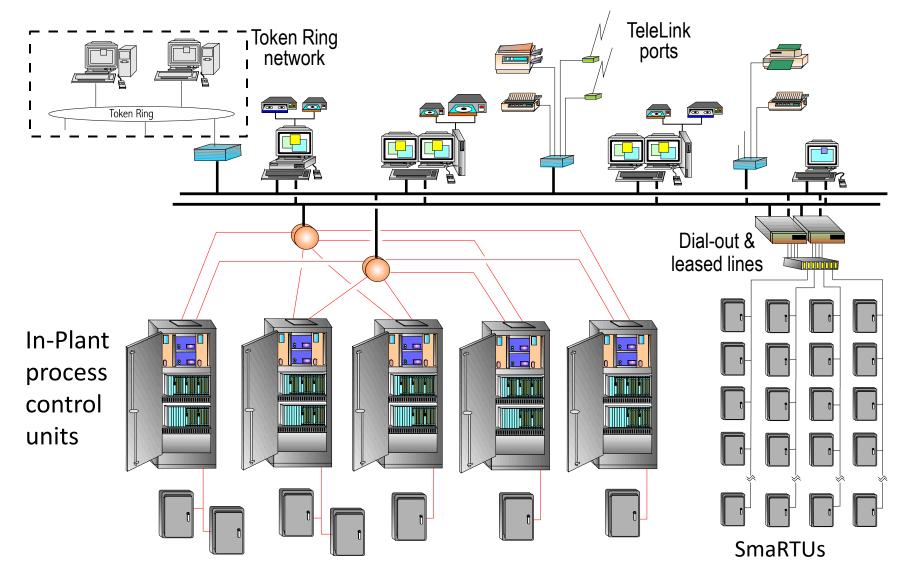
TIS-4000 Systems



Hathaway

TIS-4000 Systems

Industrial Automation, Inc. Western Lake Superior Sanitary District



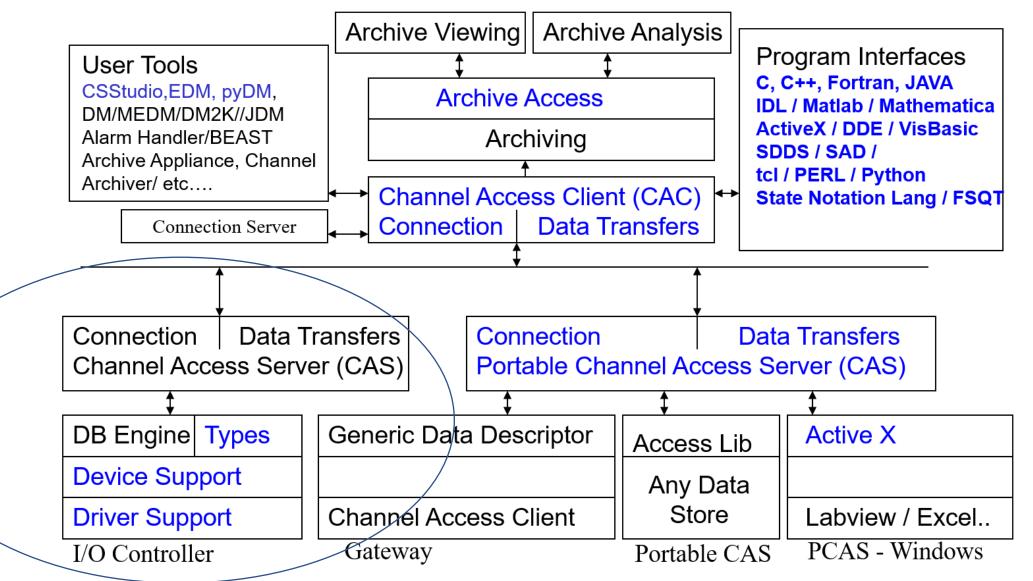
EPICS Is an Established Standard Toolkit

- The Experimental Physics and Industrial Control System is used successfully in both Industry and Research Facilities since the late 1990's
- EPICS is a set of tools (not a solution) that have been applied to small and large systems worldwide.
- Domain Expertise Applies Tools to Effectively, Efficiently and Reliably Solve a wide variety of Process Control Problems.
- Commercial Companies have a lot more time to create marketing material.

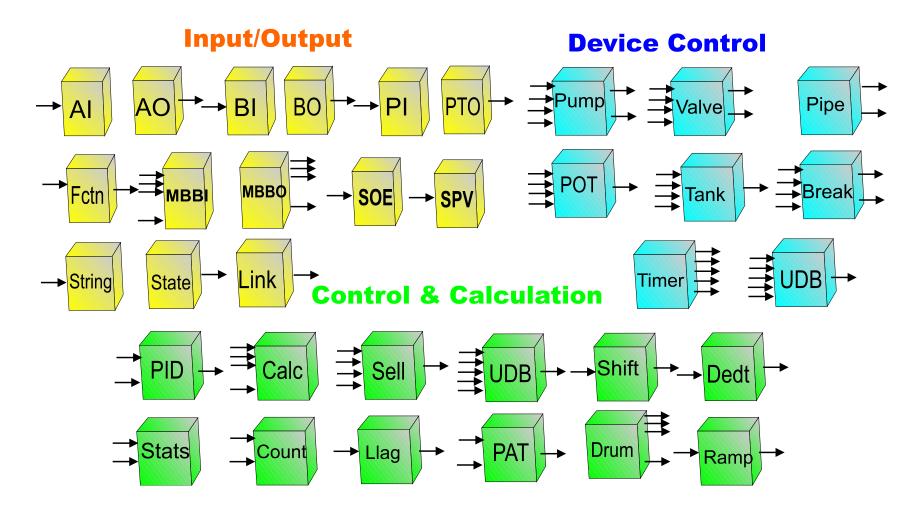
EPICS Architecture has Significant Differences compared to Industrial Control Systems

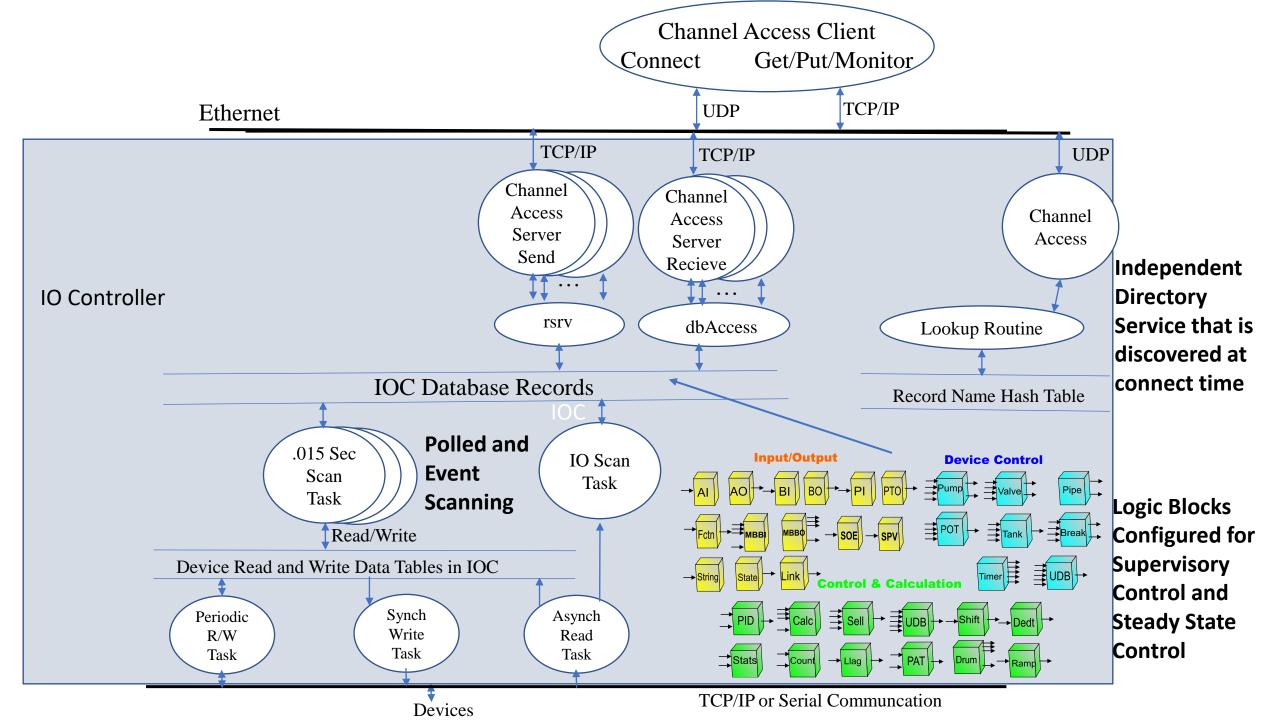
- A three-tier architecture was deemed the "standard model" for control systems: Field IO/Instrumentation, Computer Front End as Data Servers and Client Applications
- The unique feature of EPICS was to create well defined interfaces at all level of the software to support the independent development and extensions to EPICS base (Channel Access Protocol and the Process Database).
- Configuration tools are provided to reduce the programming time and risk. The same EPICS core runs at all facilities.
- The open source collaboration worked cooperatively or individually to extend the functionality as needed.

Interfaces Support Independent Development



Process Database Configuration of DBTypes – Building Blocks that form atomic operations

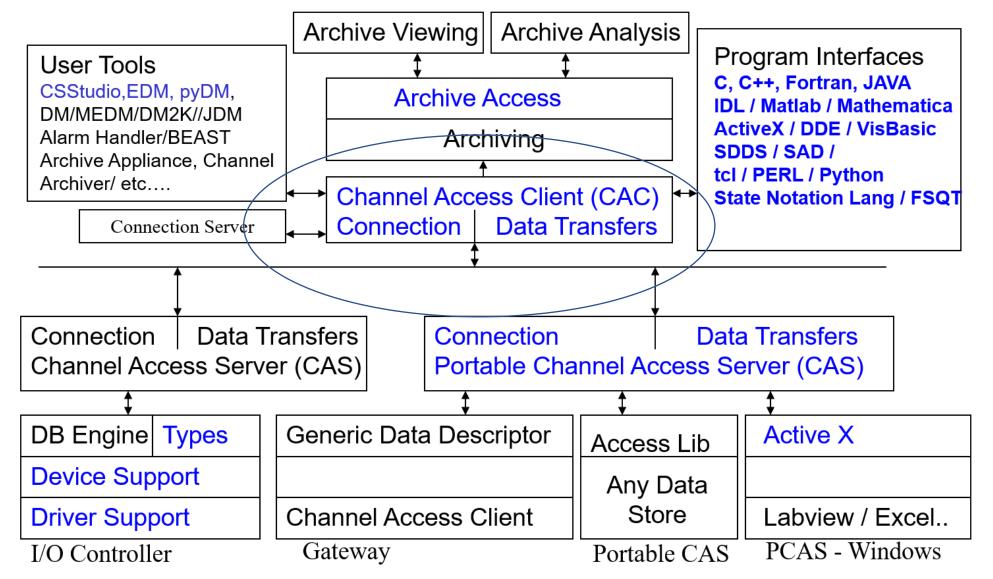




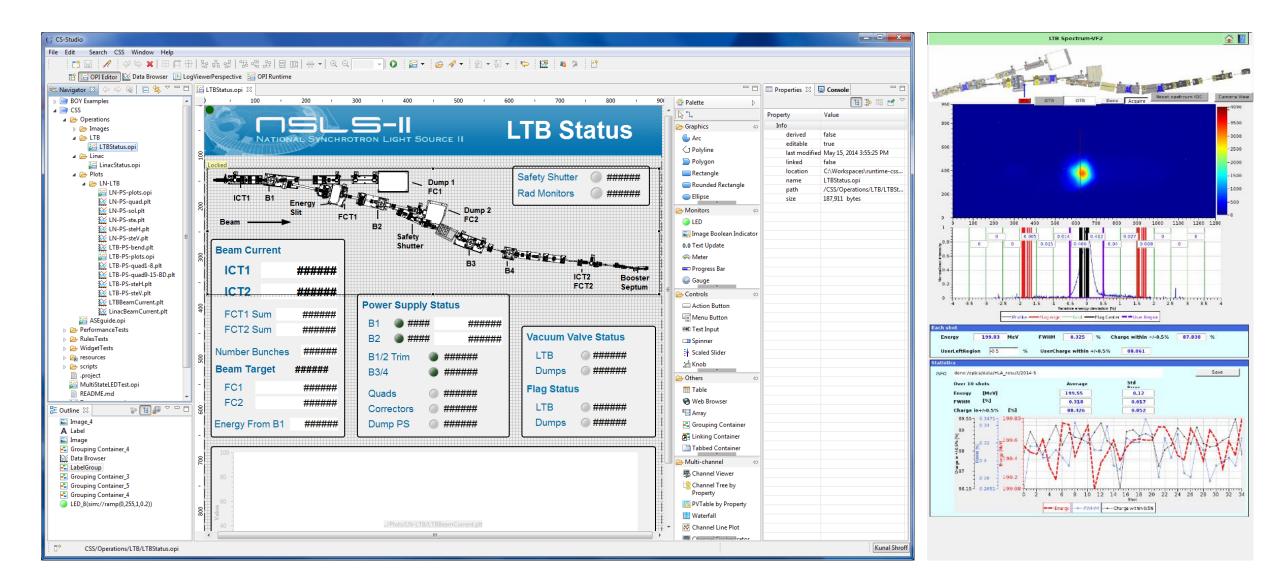
Getting the time stamp into a record

- Allow the device support to provide the timestamp from the Device.
- Get the time stamp from the local time server NTP or PTP
- Use the time stamp of the Record from which a value was read

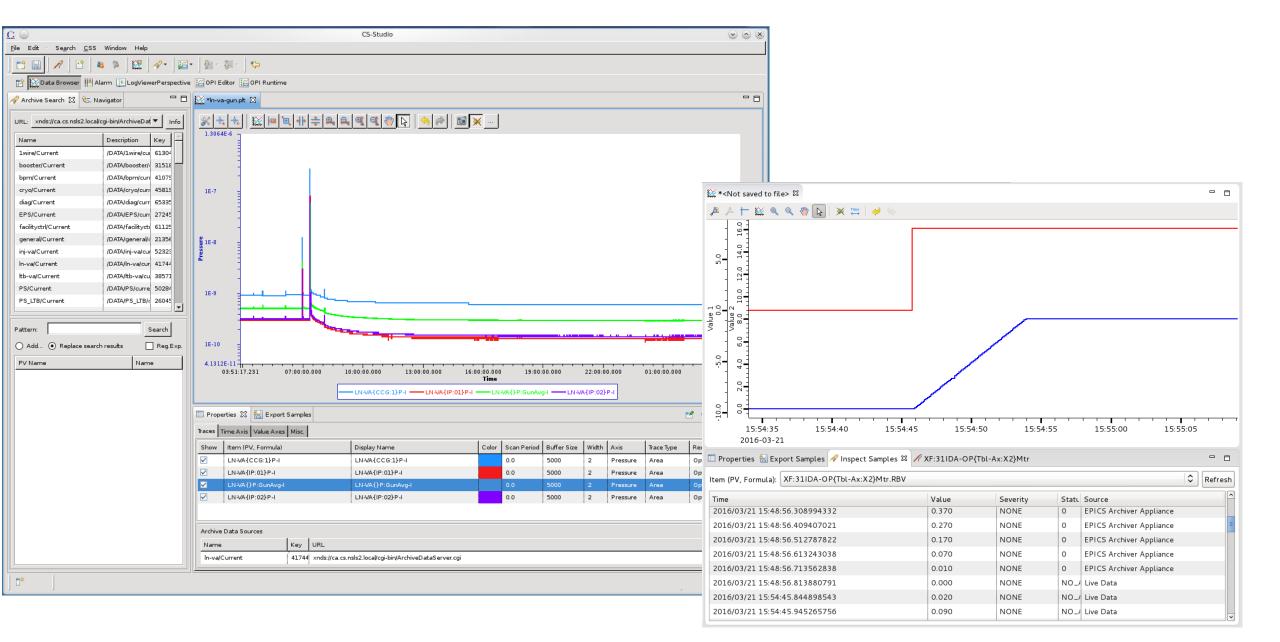
Interfaces Support Independent Development



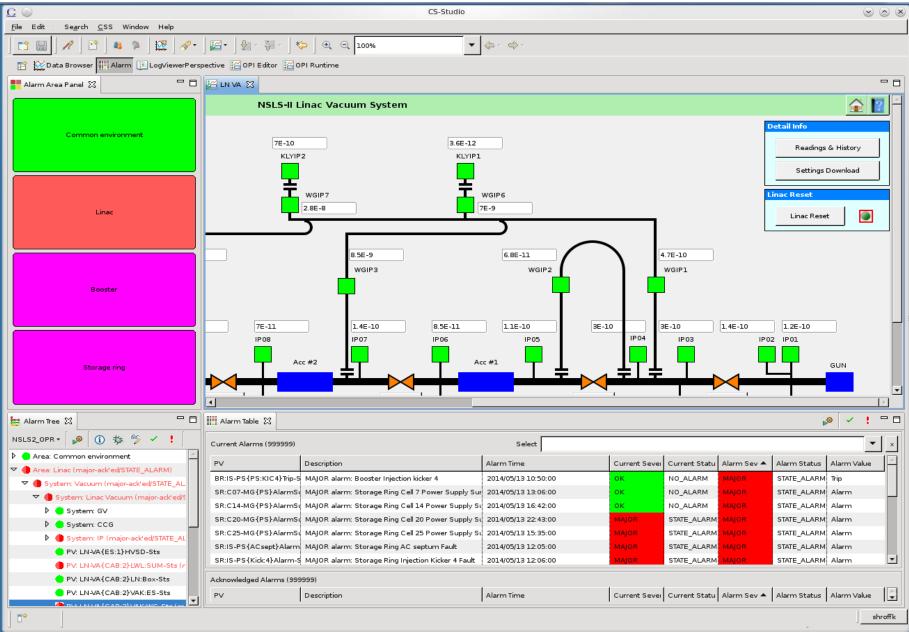
Synoptic Editor and Runtime



Archive Appliance



Alarm Viewer



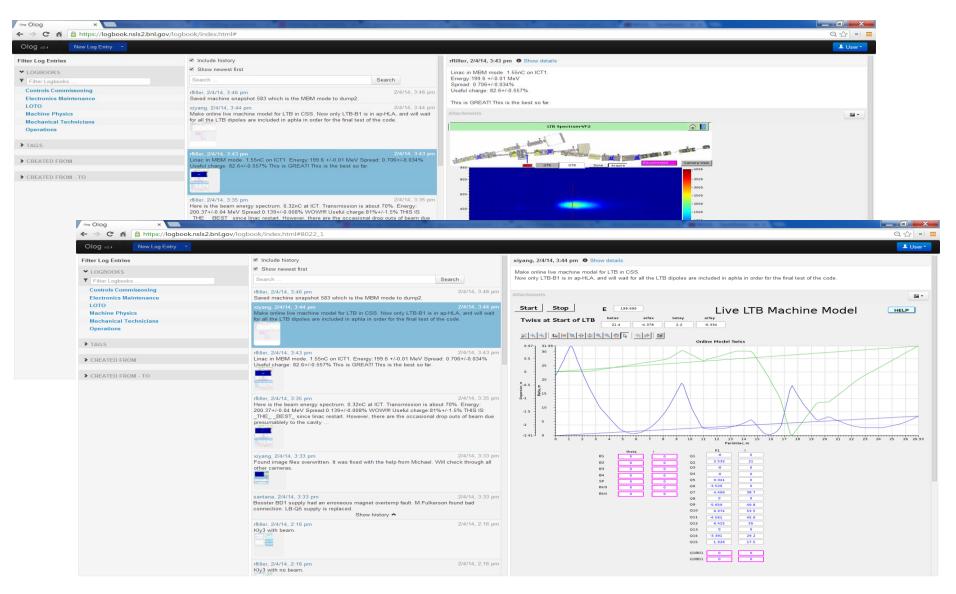
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Scan Service

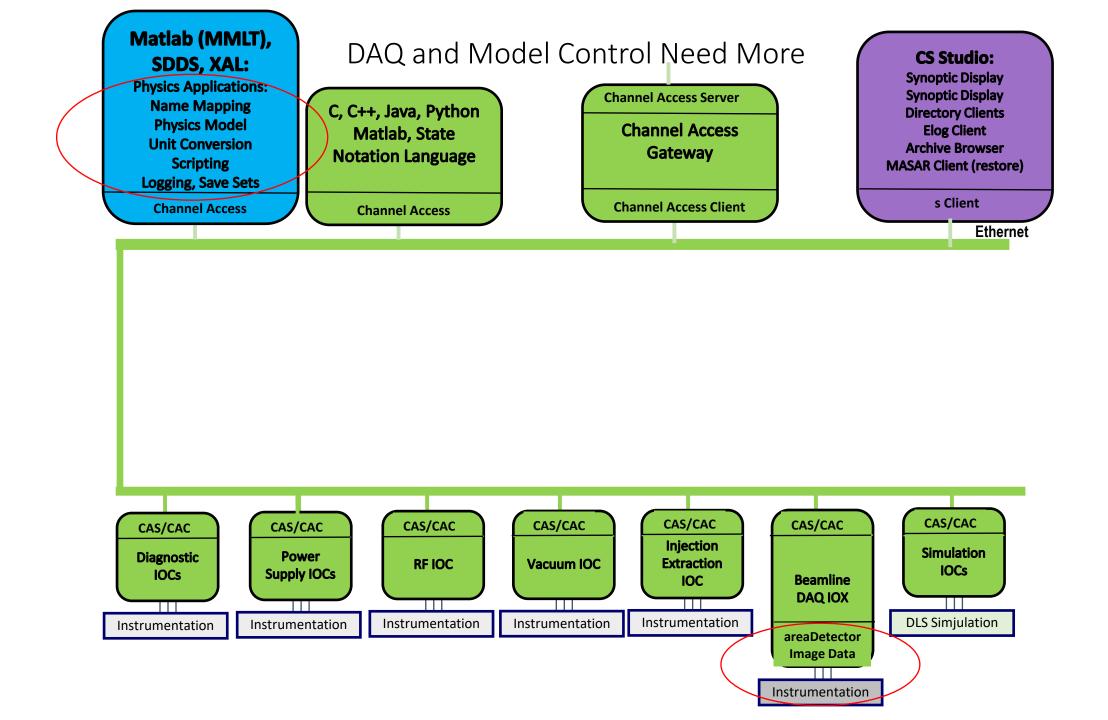
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L2,4,7 Counter 10000 01:00:00 Hz, 1mm X step 2 0.7 bm2 100000 3600 Hz, 1mm X step 3 0.8 bm2 100000 3600 Hz, 1mm X step 3 0.8 bm2 100000 3600 Hz, 1mm X step 4 0.9 bm2 100000 3600 12 30Hz, 0.4mm Y Step 0 -2 1 30 30 2.88 2 neutrons 100000 3600 13 30Hz, 0.4mm Y Step -1.6 1.1 neutrons 100000 3600 14 30Hz, 0.4mm Y Step -1.2 1.2 1.2 1.2 1.2 1.2	position	Wait Fo	r Value	E1 A A BL7:CS:IPTS 2 1105	B Comment 60 60Hz, 1mm X step 60Hz, 1mm X step 60Hz, 1mm X step 1Hz, 1mm X step Hz, 1mm X step Hz, 1mm X step	ROT C D E X Y HRO -5 0 -4 -3 -2 -1	F G T Speed1 Speed2 0 60 60 0.1 0.2 0.3 0.4	H I J BL7:Choj Wavelen Wait For 1.44 1.5 bm2 bm2 bm2 bm2 bm2 bm2 bm2 bm2	K Value O 1000000 1000000 1000000 1000000	L 3600 3600 3600 3600 3600 3600
Hz, 1mm X step 3 0.8 bm2 100000 3600 uuHz, 1mm X step 4 0.9 bm2 100000 3600 12 30Hz, 0.4mm Y Step 0 -2 1 30 30 2.88 2 neutrons 100000 3600 13 30Hz, 0.4mm Y Step -1.6 1.1 neutrons 100000 3600 14 30Hz, 0.4mm Y Step -1.2 1.2 neutrons 1000000 3600	position	Wait Fo		E1 A BL7:CS:IPTS 1109 A Or Time	B Comment	ROT C D E X Y HRO -5 0 -4 -3 -2 -1 0	F G 5peed1 Speed2 0 60 60 0.1 0.2 0.3 0.4 0.5	H I J BL7:Choj Wavelen Wait For 1.44 1.5 bm2 bm2 bm2 bm2 bm2 bm2 bm2 bm2 bm2 bm2	K Value O 1000000 1000000 1000000 1000000 1000000	L 3600 3600 3600 3600 3600 3600 3600
Dull HZ, 1mm X step 4 0.9 bm2 100000 3600 12 30Hz, 0.4mm Y Step 0 -2 1 30 30 2.88 2 neutrons 100000 3600 13 30Hz, 0.4mm Y Step -1.6 1.1 neutrons 100000 3600 14 30Hz, 0.4mm Y Step -1.2 1.2 neutrons 100000 3600				E1 A BL7:CS:IPTS 1109 A Or Time	B Comment	ROT C D E X Y HRO -5 0 -4 -3 -2 -1 0 1	F G Speed1 Speed2 0 60 60 0.1 0.2 0.3 0.4 0.5 0.6	H I J BL7:Choj Wavelen Wait For 1.44 1.5 bm2 bm2 bm2 bm2 bm2 bm2 bm2 bm2 bm2 bm2	K Value O 1000000 1000000 1000000 1000000 1000000	L 3600 3600 3600 3600 3600 3600 3600 360
12 30 Hz, 0.4mm Y Step 0 -2 1 30 30 2.88 2 neutrons 100000 3600 13 30 Hz, 0.4mm Y Step -1.6 1.1 neutrons 100000 3600 14 30 Hz, 0.4mm Y Step -1.2 1.2 1.2 neutrons 100000 3600				E1 A BL7:CS:IPTS 1109 A Or Time	B Comment	ROT C D E X Y HRO -5 0 -4 -3 -2 -1 0 1 2	F G T Speed1 Speed2 0 60 60 0.1 0.2 0.3 0.4 0.5 0.6 0.7	H I J BL7:Choj Wavelen Wait For 1.44 1.5 bm2 bm2 bm2 bm2 bm2 bm2 bm2 bm2 bm2 bm2	K Value O 1000000 1000000 1000000 1000000 1000000	L 3600 3600 3600 3600 3600 3600 3600 360
13 30Hz, 0.4mm Y Step -1.6 1.1 neutrons 100000 3600 14 30Hz, 0.4mm Y Step -1.2 1.2 neutrons 100000 3600				E1 A BL7:CS:IPT 1109 3 4 Or Time 0 01:00:00	B Comment	ROT C D E X Y HRO -5 0 -4 -3 -2 -1 0 1 2 3	F G T Speed1 Speed2 0 60 60 0.1 0.2 0.3 0.4 0.5 0.6 0.7 0.8	H I J BL7:Choj Wavelen Wait For 1.44 1.5 bm2 bm2 bm2 bm2 bm2 bm2 bm2 bm2 bm2 bm2	K Value O 1000000 1000000 1000000 1000000 1000000	L 3600 3600 3600 3600 3600 3600 3600 360
14 30Hz, 0.4mm Y Step -1.2 1.2 neutrons 100000 3600				E1 A BL7:CS:IPTS 1109 0 Or Time 0 01:00:00	B Comment	ROT C D E X Y HRO -5 0 -4 -3 -2 -1 0 1 2 3 4	F G T Speed1 Speed2 0 60 60 0.1 0.2 0.3 0.4 0.5 0.6 0.7 0.8 0.9	H I J BL7:Choj Wavelen Wait For 1.44 1.5 bm2 bm2 bm2 bm2 bm2 bm2 bm2 bm2 bm2 bm2	K Value O 1000000 1000000 1000000 1000000 1000000	L 3600 3600 3600 3600 3600 3600 3600 360
15 30Hz, 0.4mm Y Step -0.8 1.3 neutrons 1000000 3600				E1 A BL7:CS:IPTS 1109 0 Or Time 0 01:00:00	B Comment	ROT C D E X Y HRO -5 0 -4 -3 -2 -1 0 1 2 3 4 0 -2	F G T Speed1 Speed2 0 60 60 0.1 0.2 0.3 0.4 0.4 0.5 0.6 0.7 0.8 0.9 30 30	HIJBL7:Choj Wavelen: Wait For1.441.5bm2	K Value O 1000000 1000000 1000000 1000000 1000000	L 3600 3600 3600 3600 3600 3600 3600 360
				E1 A BL7:CS:IPTS 1109 0 Or Time 0 01:00:00	B Comment	ROT C D E X Y HRO -5 0 -4 -3 -2 -1 0 1 2 3 4 0 -2 -1.6	F G T Speed1 Speed2 0 60 60 0.1 0.2 0.3 0.4 0.5 0.6 0.7 0.8 0.9 1 30 30 30	HIJBL7:Choj Wavelen: Wait For1.441.5bm2bm3bm4bm4bm5bm5bm5bm6bm7bm7bm8bm8bm9bm9bm9bm1bm2bm2bm3bm4bm4bm5bm5bm6bm7bm8bm8bm9bm9bm9bm9bm1bm2bm3bm4bm4bm5bm5bm6bm7bm8<	K Value O 1000000 1000000 1000000 1000000 1000000	L Time 3600 3600 3600 3600 3600 3600 3600 3600 3600 3600 3600 3600 3600 3600 3600 3600
16 20Us 0 dama V Chan 0.4 3.4 neutrana 3000000 2600				E1 A BL7:CS:IPTS 1109 0 Or Time 0 01:00:00	B Comment	ROT C D E X Y HRO -5 0 -4 -3 -2 -1 0 1 2 3 4 0 -2 -1.6	F G T Speed1 Speed2 0 60 60 0.1 0.2 0.3 0.4 0.5 0.6 0.7 0.8 0.9 1 30 30 30	HIJBL7:Choj Wavelen: Wait For1.441.5bm2bm3bm4bm4bm5bm5bm5bm6bm7bm7bm8bm8bm9bm9bm9bm1bm2bm2bm3bm4bm4bm5bm5bm6bm7bm8bm8bm9bm9bm9bm9bm1bm2bm3bm4bm4bm5bm5bm6bm7bm8<	K Value O 1000000 1000000 1000000 1000000 1000000	L Time 3600 3600 3600 3600 3600 3600 3600 3600 3600 3600 3600 3600 3600 3600 3600 3600

Operator Logbook – Web Viewer



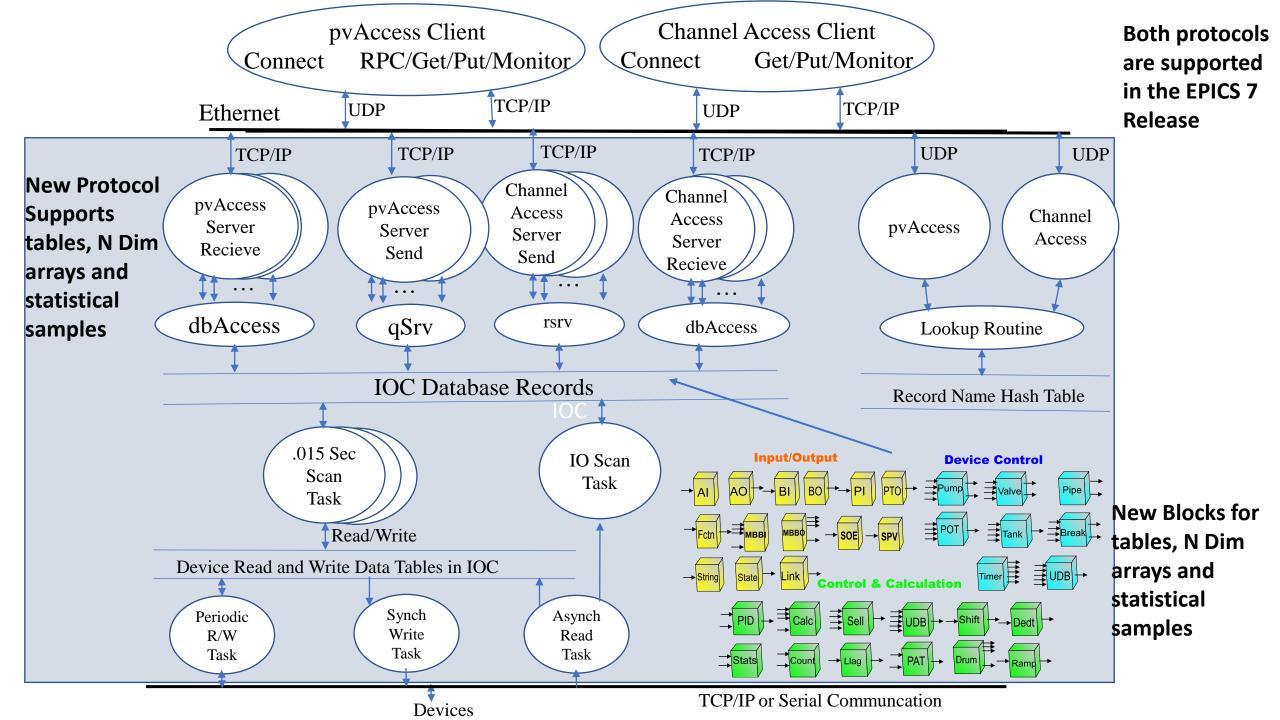
EPICS Architecture V3 (1991 – present)

- Has been successfully deployed internationally for a wide variety of facilities over a wide range of domains.
- The Configuration tools for SCADA and DCS have been demonstrated.
- A multitude of facilities have integrated a wide range of I/O.
- The Channel Access Interface has been used on all platforms and programming languages to develop general purpose and application specific clients.
- Scalar data is well supported in V3, however, faster ADCs and real time access to SQL and non-SQL databases provide new opportunities.

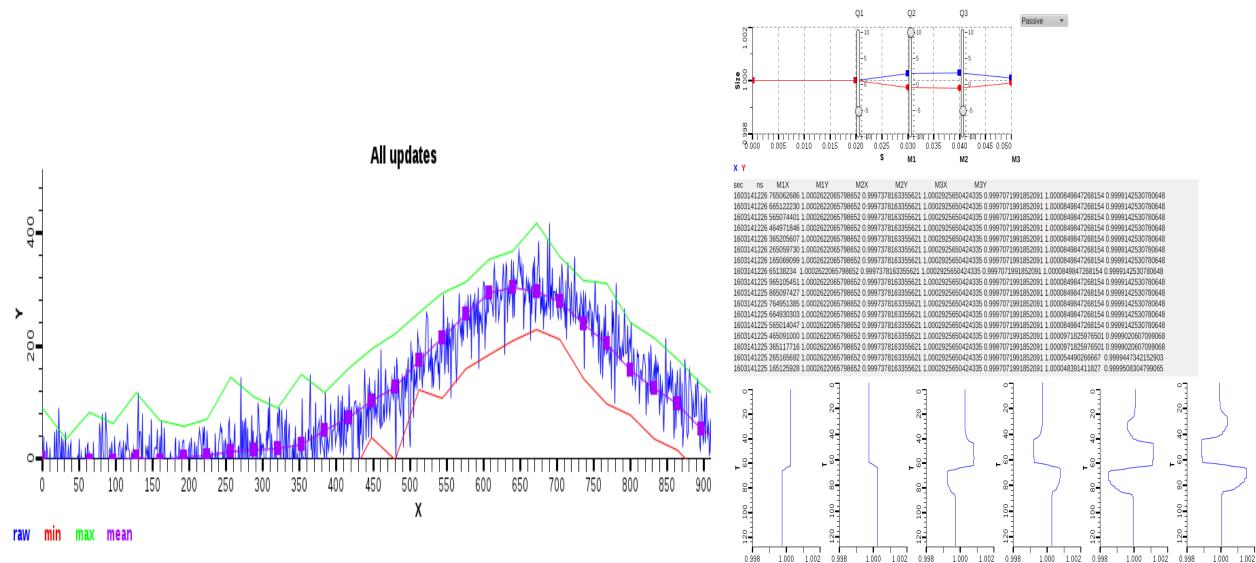


New Standards Create Opportunities to Improve Capabilities

- Expand Process Database
 - N Dimensional Arrays
 - Tables
 - Statistical Samples
- Middle Layer Services Improve capabilities
 - Directory Service hierarchical views of 1M Process Variables
 - Aggregate Alarm Data
 - Snap shot data
- Phoebus /CS Studio
 - Data passing between client applications
- Data Management Tools from configuration to snapshot data
 - Inventory, Device Types, electronic travelers, machine design



Client Viewer for statistics and Table Data



M1X

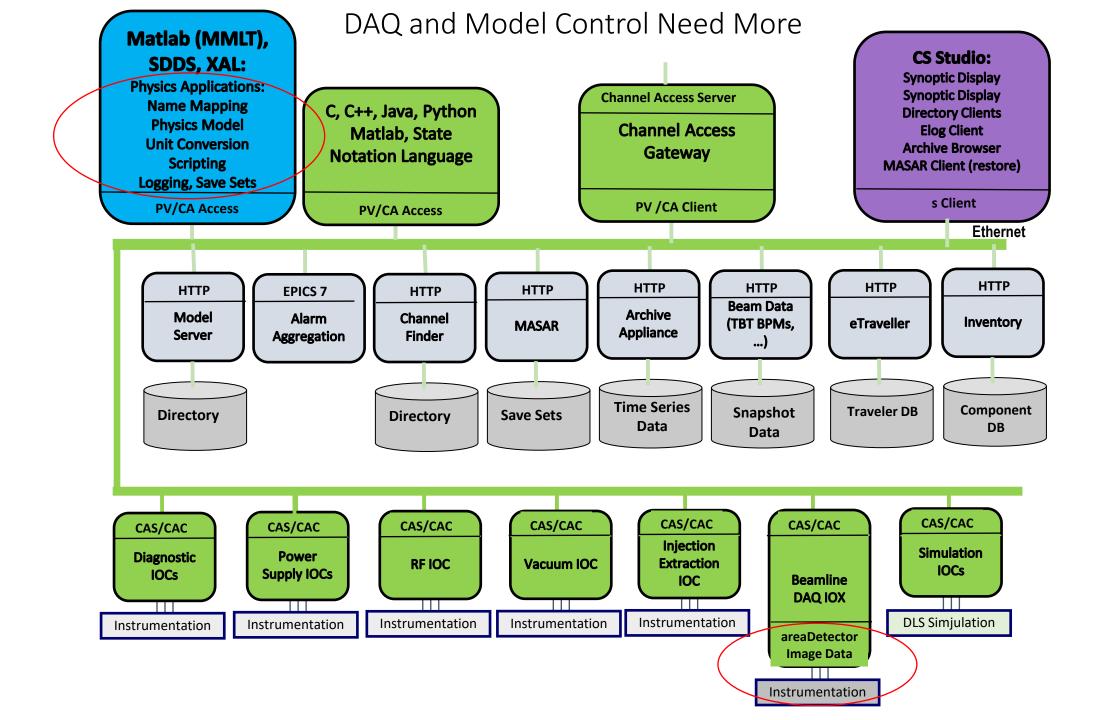
M1Y

M2X

M2Y

M3X

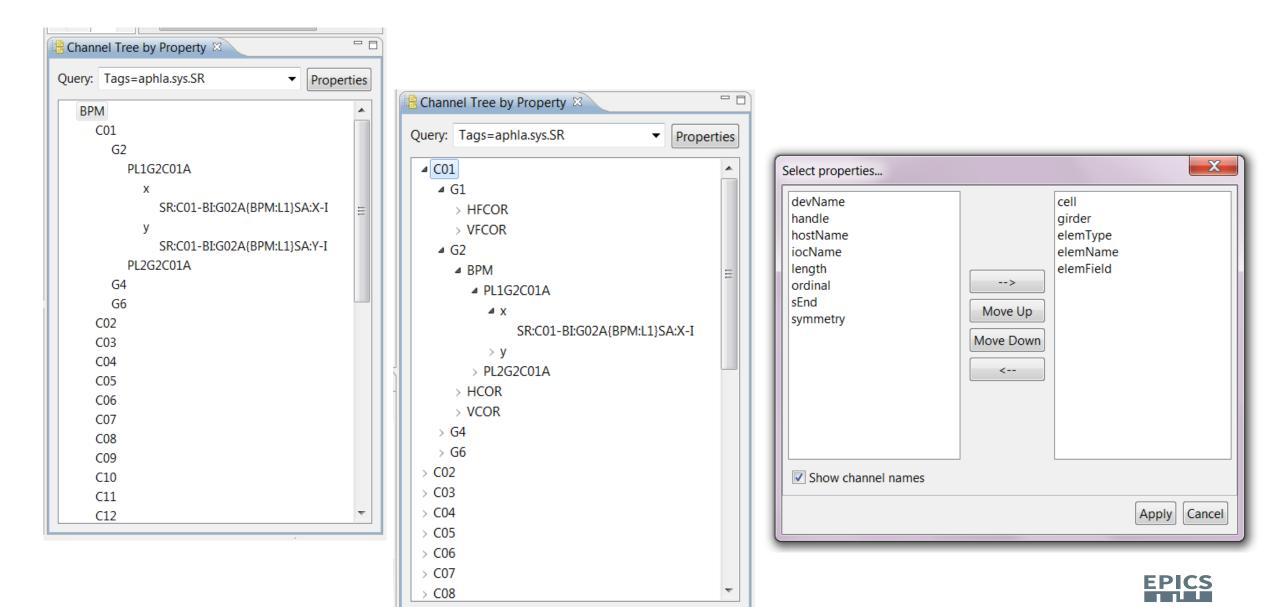
M3Y



Directory Service - Alias Properties

R:CO* elemType=ł	HCOR, BPM Tags=	aphla.sys.SR=									v
Channel Name	Owner	handle	girder	cell	ordinal	devName	elemName	elemField	elemType	sEnd 💌	length
R:C01-BI:G02A	cf-update	READBACK	G2	C01	120	PL1G2C01A	PL1G2C01A	x	BPM	29.9886	0.0
R:C01-BI:G02A	cf-update	READBACK	G2	C01	120	PL1G2C01A	PL1G2C01A	У	BPM	29.9886	0.0
5R:C01-BI:G02A	cf-update	READBACK	G2	C01	120	PL1G2C01A	PL1G2C01A		BPM	29.9886	0.0
5R:C01-BI:G02A	cf-update	READBACK	G2	C01	120	PL1G2C01A	PL1G2C01A		BPM	29.9886	0.0
5R:C01-BI:G02A	cf-update	SETPOINT	G2	C01	120	PL1G2C01A	PL1G2C01A		BPM	29.9886	0.0
R:C01-BI:G02A	cf-update	SETPOINT	G2	C01	120	PL1G2C01A	PL1G2C01A		BPM	29.9886	0.0
5R:C01-MG:G02	cf-update	SETPOINT	G2	C01	125	CL1G2C01A	CXL1G2C01A	x	HCOR	30.6673	0.2
R:C01-MG:G02	cf-update	READBACK	G2	C01	125	CL1G2C01A	CXL1G2C01A	x	HCOR	30.6673	0.2
R:C01-MG:G02	cf-update	READBACK	G2	C01	133	CL2G2C01A	CXL2G2C01A	x	HCOR	32.1047	0.2
R:C01-MG:G02	cf-update	SETPOINT	G2	C01	133	CL2G2C01A	CXL2G2C01A	x	HCOR	32.1047	0.2
R:C01-BI:G02A	cf-update	READBACK	G2	C01	138	PL2G2C01A	PL2G2C01A	У	BPM	32,5523	0.0
R:C01-BI:G02A	cf-update	READBACK	G2	C01	138	PL2G2C01A	PL2G2C01A	x	BPM	32,5523	0.0
R:C01-BI:G02A	cf-update	SETPOINT	G2	C01	138	PL2G2C01A	PL2G2C01A		BPM	32,5523	0.0
R:C01-BI:G02A	cf-update	SETPOINT	G2	C01	138	PL2G2C01A	PL2G2C01A		BPM	32,5523	0.0
5R:C01-BI:G02A	cf-update	READBACK	G2	C01	138	PL2G2C01A	PL2G2C01A		BPM	32,5523	0.0
R:C01-BI:G02A	cf-update	READBACK	G2	C01	138	PL2G2C01A	PL2G2C01A		BPM	32,5523	0.0
R:C01-MG:G04	cf-update	READBACK	G4	C01	150	SQMG4C01A	CXMG4C01A	x	HCOR	36.7222	0.2
R:C01-MG:G04	cf-update	SETPOINT	G4	C01	150	SQMG4C01A	CXMG4C01A	x	HCOR	36.7222	0.2
R:C01-BI:G04A	cf-update	SETPOINT	G4	C01	161	PM1G4C01A	PM1G4C01A		BPM	38.3018	0.0
R:C01-BI:G04A	cf-update	SETPOINT	G4	C01	161	PM1G4C01A	PM1G4C01A		BPM	38.3018	0.0
R:C01-BI:G04A	cf-update	READBACK	G4	C01	161	PM1G4C01A	PM1G4C01A	x	BPM	38.3018	0.0
5R:C01-BI:G04A	cf-update	READBACK	G4	C01	161	PM1G4C01A	PM1G4C01A		BPM	38.3018	0.0
R:C01-BI:G04A	cf-update	READBACK	G4	C01	161	PM1G4C01A	PM1G4C01A		BPM	38.3018	0.0
R:C01-BI:G04A		READBACK	G4	C01	161	PM1G4C01A	PM1G4C01A	У	BPM	38.3018	0.0
R:C01-BI:G04B	cf-update	SETPOINT	G4	C01	171	PM1G4C01B	PM1G4C01B		BPM	40.5345	0.0
R:C01-BI:G04B		SETPOINT	G4	C01	171	PM1G4C01B	PM1G4C01B		BPM	40.5345	0.0
5R:C01-BI:G04B		READBACK	G4	C01	171	PM1G4C01B	PM1G4C01B		BPM	40.5345	0.0

Directory Service – Configures Hierarchy



Directory Service – Used to provide parameter displays

Query: Tags=aphla.sys.SR cell=C	01	 Row: 	devName 👻	Column:	elemField		
devName \ elemField	x		у				
CH1G6C01B	0.0		0.0				
CH2G6C01B	0.0		0.0				
CL1G2C01A	0.0		0.0				
CL2G2C01A	0.0		0.0				
CM1G4C01B	0.0		0.0				
FL1G1C01A	0.0		0.0				
FL2G1C01A	0.0		0.0				
FM1G4C01A	0.0	0.0					
PH1G6C01B	-7.216569742425744E-7		0.0				
PH2G6C01B	-2.1431258791651994E-7		0.0				
PL1G2C01A	-1.500986653185494E-6		0.0				
PL2G2C01A	-1.806087679109317E-6		0.0				
PM1G4C01A	1.6492499142893348E-6	0.0					
PM1G4C01B	1.3008445367347664E-6		0.0				
SQMG4C01A	0.0		0.0				

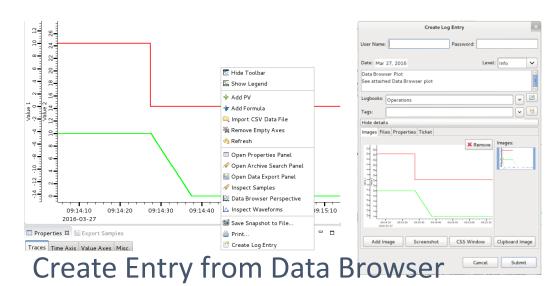
Phoebus uses Directory Service to improve workflow

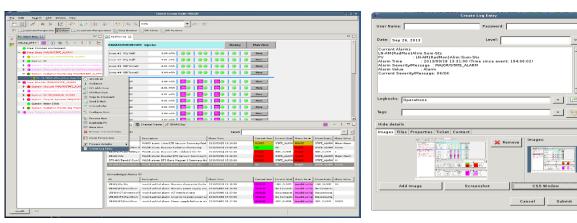
E Channel Orchestrator										
Query: V*SM*SP									✓ Sconfigure	
Channel	hostName	Min	Value	Max	Weight	-	Step1	Step2	Step3	
V:1-SR:C14-MG:G4{SM2H:1623}Fld:SP	virtac	12.922061	14.357846	15.793631	1.0	=	15.3578466516	16 2570 466		-5
V:1-SR:C19-MG:G4{SM1:2188}Fld:SP	virtac	-10.85894	-12.06549	-13.27204	1.0		-11.0654912139	🖊 sim://noise 🛛	3 💼 🖥 ▼ 🖓	•
V:1-SR:C02-MG:G4{SM2H:279}Fld:SP	virtac	12.922061	14.357846	15.793631	1.0		15.3578466516	PV Formula: LT	B-BI{BPM:6}Pos:X-	
V:1-SR:C12-MG:G4{SM1:1404}Fld:SP	virtac	-11.74268	-13.04742	-14.35216	1.0		-12.0474266781			n
V:1-SR:C06-MG:G4{SM1:718}Fld:SP	virtac	-10.85894	-12.06549	-13.27204	1.0		-11.0654912139	Value: -3.5	History (0 matching items)	
V:1-SR:C07-MG:G4{SM1:833}Fld:SP	virtac	-10.85894	-12.06549	-13.27204	1.0		-11.0654912139	Timestamp:	ChannelFinder (5 matching items)	
V:1-SR:C14-MG:G4{SM1:1628}Fld:SP	virtac	-11.74268	-13.04742	-14.35216	1.0		-12.0474266781		LTB-BI{BPM:6}Pos:X-SQHST	
V:1-SR:C21-MG:G4{SM1:2412}Fld:SP	virtac	-10.85894	-12.06549	-13.27204	1.0		-11.0654912139	New Value:	LTB-BI{BPM:6}Pos:X-RMSHST	
V:1-SR:C05-MG:G4{SM1:609}Fld:SP	virtac	-10.85894	-12.06549	-13.27204	1.0		-11.0654912139		LTB-BI{BPM:6}Pos:X-I	
V:1-SR:C24-MG:G4{SM2H:2754}Fld:SP	virtac	12.922061	14.357846	15.793631	1.0	-	15.3578466516	🔸 Data soi	LTB-BI{BPM:6}Pos:X-SQ	
Step Count: 3 Step Size: 1	Generate Set	points						Type: VDou	LTB-BI{BPM:6}Pos:X-RMS	
				App	oly			Display limi		
								Alarm limits		
								Warning limits:	: -3 - 3	
								Control limits:	-5 - 5	
								Unit:	x	
								Status: Connecte	ed	-



Operator Log – Entry Creation

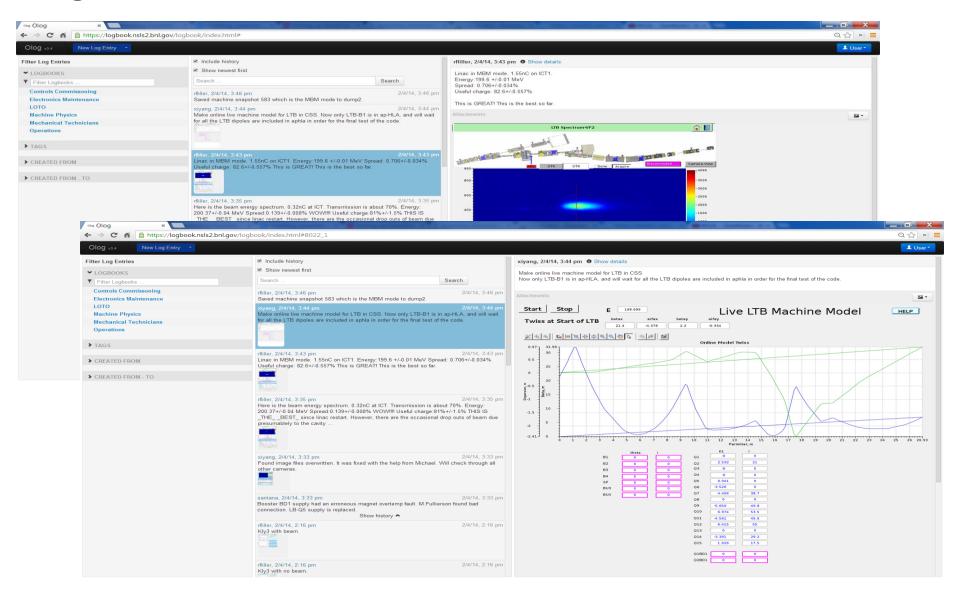
File Edit Search CS-	Studio Window Help
	🗱 📾 📓 × 🖨 🖋 ×
Create L	.og Entry ×
Jser Name: olog-user	Password:
Date: Mar 27, 2016	Level: Info 🗸
username: olog-user password: 1234	E
Logbooks: Operations	Image:
Tags:	
Details	
	Cancel Submit
Create En	Time Owner Text Attachments Logbooks Tags Properties





Create Entry from Alarm Viewer

Operator Log – Web Viewer



Send PV to any other CSS **PV tool**

Record Type:

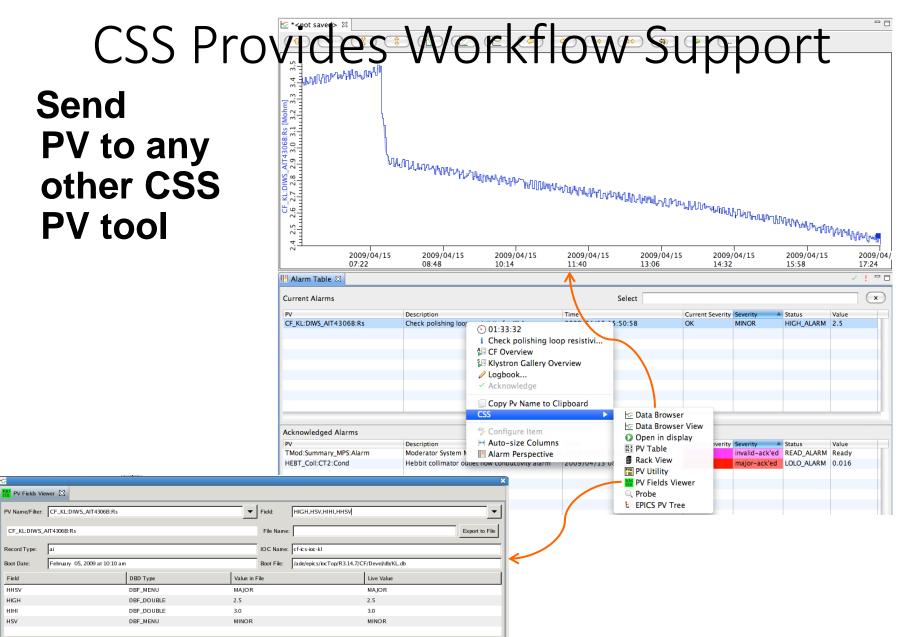
Boot Date:

Field HHSV

HIGH

ніні

HSV

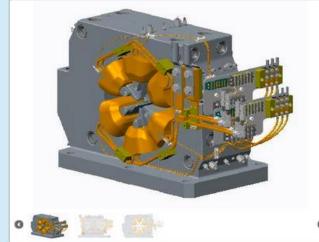


Data Management Tools – electronic traveler

			Controis Travelor Ro											
test1			New Form	avelers	C Reload	Meta	Profie	Users i About						
	label 🗌 checkbox text	C 4 6	My forms	Copy	Print Save •									
	test area inside the input		Shared forms	10	records per pa	9¢						Searc	٤[
	test area inside the input		Group shared forms	т	ntle 4	Status	Devices	Shared with	Shared groups	Created by	Created	Deadline by	Upda	Estimated progress
	some hint		My travelers	18 U	IN-CMA553-	active	\$53002			victory	2 hours	vict	ary 31	7/46
			Shared travelers	G	AVH-ASSY						ago		minu ago	
	Label test area Keep the label brief and unique Placeholder inside the input		Group shared travelors		SRF Facility Weekly Maintenance	active		Whatey, Joseph, Clark, Alex, Whetstone, Caleb, Metzgar, Ethan, Victory, Daniet, Malloch, Ian; Barkor, Bfan, Popislarski, Laura, Ignatowski, Daniel; Oja, Byron; Elliott, Kyle; Dobrzynski, Alyssa; Brunk, Ryan		ignatows	4 hours ago	igns	tows 43 minu ago	
	Row 3		Active travelers	C L	JN-CMAS53- SAVH-HPR!	active	S53-002		LAB FRIB ASD SRF. LAB FRIB ASD SRF. CavityProcessing	malloch	3 days ago	vich	ary 3 day ago	25 (1320)
	Help some hint		Frozen travelers		IN-CMAS29-CAV- SETCH	active	\$29-001		LAB.FRIB.ASD.SRF. LAB.FRIB.ASD.SRF.CavityProcessing	malloch	3 days ago	mai	och 2 hou ago	rs 22/28
	Done		Archived travelers	C U	IN-CMA553- CAVH-ASSY	active	53-002			victory	3 days ago	vich	ary 3 day ago	s 946
test				C	JN CMAS.005 CAV-USC DEGREASE	active	S85-004			barkerbr	4 days ago	ban	erbr 4 day ago	rs 0/0
the form self					IN-CMAS53- CAVIL-HPR!	active	S53-002		LAB FRIB ASD SRF. LAB.FRIB ASD SRF. CavityProcessing	malloch	4 days ago	mail	och 4 day ago	5 17/20
FRIB	Form builder	Male can de la ferre constructure			×		E A			velianof	4 days ago	veli	nof 4 day ago	s <u>1/54</u>
		Bithlis: active Devices: ReA3-08-PPD5 JUDIT IN Congarian John Veralation video rolling Tere Alexa Literate								barkerbr	5 days ago	barl	erta 4 day ago	rs 🚺 10/43
		Summary experiment date 10 lat 12-35 every 2016-05-02 experiment date in onjoil from upp: experiment date in onjoil from upp:								velianof	5 days ago	vola	inof 5 day ago	rs 1/54
		east, not choronad Henge, tar Ingun Image: no ngun trem waer						Shared with	Shared groups	Created b		Up	date	
		Description: I vanit Fasdfas usaans konday laaten yn Epits Stadouw an canesa yn ach maraat, kond ronfordat, yn Stat I am upaws by tud an annoag, May tein ysch, proc'h pin												4 5 Next→ Release 2.3.
		first												
		approximation Implify the property of the proper												
	Tr	aveler Page												

Data Management Tools – inventory/installation





omponent Instance	Properties					1
					P 2	E H
Type 💠		Tag 🗘	Value \$	Units ¢	Dynamic 🗘	Actions
Traveler Instance (El	ectronic)		EAA to 314			00
Traveler Instance (El	ectronic)		S1A001 EAA to 314			00
Traveler Instance (IC	MS)		APSU 1694686			0
Traveler Instance (El	ectronic)		314 to EAA			00
omponent Propertie	:S					
					P 2	
Type ≎	Tag ≎		Value \$	Unit:	s Dynamic	Actions
PDMLink Drawing	Yoke	<u>U2</u>	21020202-112000.drw		-8	00
Purchase Requisition		<u>F5</u>	<u>-013070</u>			0
Image	Iso View					0
PDMLink Drawing	Magnet Assembly	<u>U2</u>	21020202-112100			00
Image	Front View			2		0
Image	Upstread View					0
Component Design	Reference Design		MM SEXTUPOLE 21020202-112100			0
Traveler Template (Electronic)			S-U Rigging Daily Lift ecklist			0

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EPICS 7 Enables New Solutions

- EPICS 7 is the EPICS 3 and EPICS 4 protocols running simultaneously where V4 has new capabilities in Normative Data Types and Communication Mechanisms.
- The Middle Layer Services provides an aggregation layer allows for use in multiple user interfaces tools.
- New Tools are developed to improve control system development
- The collaboration continues to contribute to this open source control system with concern for the large installed base.

Commercial Support for EPICS

- There are commercial applications that use EPICS.
- There are a number of companies that sell their instrumentation with EPICS support such as drivers or a full implementation provided
- Companies are providing support for EPICS develop or use in applications: Observatory Sciences, CosyLab and Osprey Distributed Control Systems.
- As EPICS is open source, anyone could be using it and there could be more that are not listed here.

Conclusions

- Architectural Features of EPICS support Industrial and Research Control Systems.
- EPICS is used in Industrial Applications and Research Successfully for over 30 years.
- The open source community continues to support and extend EPICS to support new technology in control applications.